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# TUHINA TRIPATHI

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## EDUCATION

### University of Colorado Boulder

*Master of Science in Computer Science*

**Boulder, CO**

AUG 2021 — MAY 2023

- Coursework: Advanced Robotics, Robotic Manipulation, Decision Making under Uncertainty, Theoretical Foundations of Autonomous Systems, Design, and Analysis of Algorithms, Datacentre Scale Computing

### Delhi Technological University

*Bachelor of Technology in Information Technology*

**Delhi, India**

AUG 2015 — MAY 2019

- Coursework: Computer Vision, Image processing, Machine Learning, and AI, Pattern Recognition, Software Development, Natural Language Processing, Data Mining, Information Security

## RESEARCH INTERESTS

My research interests are in Learning from Demonstrations (LfD), safety in HRI, Reinforcement Learning.

## EXPERIENCE

### GRADUATE RESEARCH ASSISTANT

*CAIRO Lab, University of Colorado*

**SEPT 2021 — Present**

*Boulder, CO*

- Developing an algorithm using Inverse Reinforcement Learning to learn human preferences and evaluate the preference information to ensure safety
- Implementing the proposed algorithm on the OpenAI gym highway driving environment. Also implemented it on AWS DeepRacer to record real-world trajectories and evaluate the human demonstrator's preference in real-time

### RESEARCH ASSISTANT

*Emotive Computing Lab, University of Colorado*

**AUG 2021 — DEC 2021**

*Boulder, CO*

- Worked on designing, writing, and testing python code for an ML wrapper library used internally within the lab that worked with multiple backends such as sklearn and TensorFlow.
- The library integrated with and supported research development in various areas such as eye tracking, speech and language processing, physiological sensing, computer vision, and machine learning.

### SOFTWARE DEVELOPMENT ENGINEER

*Citicorp Services India Pvt. Ltd.*

**JUL 2019 — JUN 2021**

*Pune, India*

- Swap Data Reporting Engine: Developed an end-to-end enrichment solution for data patching of trades using Springboot and Angular7. The tool reduced inconsistencies on the Production database by 65%
- Compliance Data Engine: Implemented 'Advanced Search' functionality on Elasticsearch that reduced average query response time by 80%. Also worked on creating CI/CD pipeline for the project and responsive templates for CitiCODE dashboard

### RESEARCH INTERN

*Indian Institute of Technology*

**AUG 2018 — OCT 2018**

*Delhi, India*

- Implemented a GAN-based latent fingerprint enhancement algorithm that improved the quality of fingerprint images while preserving the ridge structure (Used IIITD-MOLF Dataset)
- NFIQ scores of enhanced images were three times lower than state-of-the-art approaches (around 1.88%). The improved quality fingerprints further boosted latent fingerprint recognition performance.

### RESEARCH AND DEVELOPMENT INTERN

*Nucleus Software Exports Ltd.*

**JUN 2018 — JUL 2018**

*Noida, India*

- Developed a Code Generator that transformed GUI screenshots into front-end code that reduced the hours spent by developers by 8hr/week on average. The solution was deployed end-to-end as a developer tool on Production and used by multiple internal teams in the company.
- Developed a multi-lingual chat bot to communicate in Hindi and Punjabi. The chat bot was built upon the RASA framework and was capable of retaining the context of long conversations (over 8 messages)

<https://www.overleaf.com/project/63389ae6a8bb2b8fe7949e41>

## PROJECTS

### IRL INTERACTIVE GAME TO LEARN HUMAN-LIKE OPPONENT BEHAVIOUR

*Project for ASEN 5519 - DMU*

*Spring 2022*

- Developed an interactive grid-based pathfinding game to learn human-like opponent behavior using Inverse Reinforcement Learning.
- Used a maximum entropy formulation and state visitation frequencies to learn a reward structure from the demonstrations

## DYNAMIC OBSTACLE AVOIDANCE IN SHARED HUMAN-ROBOT WORKSPACE

Project for CSCI 7000 - Robotic Manipulation

Spring 2022

- Developed a method to perform a human-robot collaborative task of clearing cans from a tabletop using the UR5e robot arm in the real-world Webots simulator. The method predicts human behavior and plans the motion of the robot arm accordingly.
- The robot maintains a belief over the human's intended goal, continually updating based on the human's motion at each time step. The manipulator then tries to figure out the best action to execute in the environment by reasoning over the uncertainty in human intention estimation using a POMDP framework.

## IMITATING HUMAN-LIKE DRIVING USING INVERSE RL IN WEBOTS

Project for CSCI 5302 - Advanced Robotics

Fall 2021

- Implemented a Maximum Entropy Deep Inverse RL approach on human-like demonstration data. The data was generated using the vehicle "Tesla Model 3" on Webots Robot simulator, driven around using keyboard controls.
- A deep neural network with two hidden layers of dimension 3 was used to estimate the reward structure. The state space was discretized and state visitation frequencies were used as features to learn the weights for the network.
- The obtained policy showed promising results by exhibiting driving behavior that was very close to the human demonstrator.

## BIO-METRIC IDENTIFICATION AND FINGERPRINT PERCEPTIVITY ENHANCEMENT

Undergraduate Major Project

2019

- Performed fingerprint enhancement using short-term Fourier Transform and Contextual filtering, to help intensify the ridges and minutiae [Dataset: 12k images from Optical and Capacitive sensors]. Enhanced images fed into a CNN for feature extraction. Achieved an accuracy of 98.32% with a significantly less False Acceptance Rate(FAR).

## AUTOMATED HATE SPEECH DETECTOR

Undergraduate Minor Project

2018

- Implemented a solution for the separation of tweets into three categories-hate speech, offensive language, and normal text. A dataset of 25k labeled tweets was used with extensive preprocessing using TF-IDF scores and POS tags.
- Model used Regression with L2 Regularization giving a precision of 0.91 and F1 score of 0.90. Additionally studied a BERT-based Transfer learning model to enhance performance for new datasets and unlabelled data.

## TEACHING

### Introduction to Robotics (CSCI 3302/ECEN 3303)

Fall'22

Teaching Assistant

- Managed weekly labs for around 60 students that included explaining and helping students implement concepts like IK, path planning, etc. on the Webots simulator
- Also responsible for conducting Office Hours and grading the Lab work and Homework.

### Starting Computing (CSCI 1300)

Spring'22, Summer'22

Teaching Assistant

- Conducted weekly recitations and office hours. Responsible for reviewing the course material and planning out final projects.

## SKILLS

**Languages** Python, C++, C, Julia, SQL, Java, Javascript

**Software & Tools:** ROS, Pytorch, Tensorflow, Webots, Linux, Angular, Spring, Elasticsearch

## ACTIVITIES

Undergraduate Research Experience program at CU Boulder

Fall 2022

Graduate Peer Mentoring Program at CU Boulder

Fall 2022

Presented a poster at the CU Boulder Annual Research Expo

Spring 2022

CitiCorp **Bronze award** for Enrichment Tool deployment on Production

2021

CitiCorp **Gratitude award** for Elasticsearch integration

2020

Teaching Volunteer at 'Teach For India'

2018 - 2019

**Best Innovation Award** at Nucleus Software for 'Code Generator'

2018

Technical Head of the Computer Society of India (CSI-DTU)

2017 - 2018

Among the Top 8 teams in SIH' 17 conducted by Govt. of India

2017